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# Large-time existence of compressible viscous and heat-conductive surface waves(Mathematical Analysis of Phenomena in Fluid and Plasma Dynamics)

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CITATION:

Tanaka, Naoto ...[et al]. Large-time existence of compressible viscous and heat-conductive surface waves(Mathematical Analysis of Phenomena in Fluid and Plasma Dynamics). 数理解析研究所講究録 1993, 824: 138-150

ISSUE DATE:

1993-03

URL:

<http://hdl.handle.net/2433/83246>

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# Large-time existence of compressible viscous and heat-conductive surface waves

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## 1 Introduction and theorem.

In this communication we are concerned with free boundary problem for compressible viscous isotropic Newtonian fluid which is formulated as follows: Find the domain  $\Omega_t \subset \mathbf{R}^3$  occupied by the fluid at the moment  $t > 0$  together with the density  $\rho(x, t)$ , velocity vector field  $v(x, t) = (v_1, v_2, v_3)$  and with the absolute temperature  $\theta(x, t)$  satisfying the system of Navier-Stokes equations

$$(1.1) \quad \begin{cases} \frac{D\rho}{Dt} + \rho(\nabla \cdot v) = 0, & \rho \frac{Dv}{Dt} = \nabla \cdot \mathbf{P} - \rho g e_3, \\ \rho c_V \frac{D\theta}{Dt} + \theta p_\theta (\nabla \cdot v) = \nabla \cdot (\kappa \nabla \theta) + \Psi, \\ x \in \Omega_t \equiv \{x' = (x_1, x_2) \in \mathbf{R}^2, -b(x') < x_3 < F(x', t)\}, & t > 0 \end{cases}$$

and the initial and boundary conditions

$$(1.2) \quad \begin{cases} (\rho, v, \theta)|_{t=0} = (\rho_0, v_0, \theta_0), & x \in \Omega_0, \\ \mathbf{P}n = -p_e n + \sigma H n, & \kappa \nabla \theta \cdot n = \kappa_e (\theta_e - \theta), \\ x \in \Gamma_t \equiv \{x' \in \mathbf{R}^2, x_3 = F(x', t)\}, & t > 0, \\ v = 0, \quad \theta = \theta_a, & x \in \Sigma \equiv \{x' \in \mathbf{R}^2, x_3 = -b(x')\}, \quad t > 0, \\ \frac{D}{Dt}(x_3 - F) = 0, & x \in \Gamma_t, \quad t > 0, \quad F|_{t=0} = F_0(x'), \quad x' \in \mathbf{R}^2. \end{cases}$$

Here,  $\nabla = (\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_3})$ ,  $\frac{D}{Dt} = \frac{\partial}{\partial t} + (v \cdot \nabla)$  is the material derivative,  $\mathbf{P} = (-p + \mu'(\nabla \cdot v))\mathbf{I} + 2\mu\mathbf{D}(v) \equiv -p\mathbf{I} + \mathbf{V}$  is the stress tensor,  $\mathbf{I}$  is the  $3 \times 3$  unit matrix,  $\mathbf{D}(v)$  is the velocity deformation tensor with the elements  $D_{ij} = \frac{1}{2}(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i})$ ,  $\Psi = \mu'(\nabla \cdot v)^2 + 2\mu\mathbf{D}(v) : \mathbf{D}(v)$  is the dissipation function,  $p = p(\rho, \theta)$  is the pressure,  $(\mu, \mu', \kappa, c_V)(\rho, \theta)$  are, respectively, coefficient of viscosity, second coefficient of viscosity, coefficient of heat conductivity, heat capacity at constant volume, which are all assumed to be known smooth functions of  $(\rho, \theta)$  satisfying  $\mu, \kappa, c_V > 0$ ,  $2\mu + 3\mu' \geq 0$ ,  $p_\rho, p_\theta > 0$ ,  $(g, \sigma, p_e, \kappa_e)$  are, respectively, acceleration of gravity, coefficient of surface tension, atmospheric pressure, coefficient of outer heat conductivity, which are all assumed to be positive constants,  $e_3 = {}^t(0, 0, 1)$ ,  $n = \frac{1}{\sqrt{1+|\nabla'F|^2}} {}^t(-\nabla_1 F, -\nabla_2 F, 1)$  is the exterior unit normal vector to  $\Gamma_t$ ,  $\nabla' = (\nabla_1, \nabla_2) = (\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2})$  and  $H = \nabla' \cdot (\frac{\nabla' F}{\sqrt{1+|\nabla'F|^2}})$  is the twice mean curvature of  $\Gamma_t$ .

We seek a solution near the equilibrium rest state  $(\rho, v, \theta, F) = (\bar{\rho}, 0, \bar{\theta}, 0)$ , where  $\bar{\theta}$  is any positive constant and  $\bar{\rho} = \bar{\rho}(x_3)$  is determined by

$$(1.3) \quad \int_{\bar{\rho}(0)}^{\bar{\rho}(x_3)} \frac{p_\rho(\eta, \bar{\theta})}{\eta} d\eta + gx_3 = 0, \quad p(\bar{\rho}(0), \bar{\theta}) = p_e.$$

We rewrite the problem (1.1), (1.2) by the change of unknown functions  $(\rho, v, \theta, F) \rightarrow (\rho + \bar{\rho}, v, \theta + \bar{\theta}, F)$  using (1.3) as follows:

$$(1.4) \quad \begin{cases} \frac{D}{Dt}(\rho + \bar{\rho}) + (\rho + \bar{\rho})(\nabla \cdot v) = 0, \\ (\rho + \bar{\rho})\frac{Dv}{Dt} = \nabla \cdot \mathbf{V} - p_\rho \nabla \rho - p_\theta \nabla \theta + (\frac{\bar{\rho}}{\bar{p}_\rho}(p_\rho - \bar{p}_\rho) - \rho)ge_3, \\ (\rho + \bar{\rho})c_V \frac{D\theta}{Dt} + (\theta + \bar{\theta})p_\theta(\nabla \cdot v) = \nabla \cdot (\kappa \nabla \theta) + \Psi, \quad x \in \Omega_t, t > 0, \end{cases}$$

$$(1.5) \quad \left\{ \begin{array}{l} (\rho, v, \theta)|_{t=0} = (\rho_0, v_0, \theta_0)(x), \quad x \in \Omega_0, \\ 2\mu \Pi \mathbf{D}(v) = 0, \quad - (p - p_e) + \mathbf{V} n \cdot n = \sigma H, \\ \kappa \nabla \theta \cdot n = \kappa_e (\theta_e - \theta), \quad x \in \Gamma_t, t > 0, \\ v = 0, \quad \theta = \theta_a, \quad x \in \Sigma, t > 0, \\ F_t + v_1 \nabla_1 F + v_2 \nabla_2 F - v_3 = 0, \quad x \in \Gamma_t, t > 0, \\ F|_{t=0} = F_0(x'), \quad x' \in \mathbf{R}^2, \end{array} \right.$$

where  $p = p(\rho + \bar{\rho}, \theta + \bar{\theta})$ ,  $\bar{p}_\rho = p_\rho(\bar{\rho}, \bar{\theta})$  etc., and  $\Pi \varphi = \varphi - n(n \cdot \varphi)$ .

We consider the problem (1.4), (1.5) in S.L.Sobolev-L.N.Slobodetskiĭ spaces. Let  $G$  be a domain in  $\mathbf{R}^n$  and  $l > 0$  be not an integer. By  $W_2^l(G)$  we mean the space of functions  $u(x)$  ( $x \in G$ ) equipped with the norm

$$\begin{aligned} \|u\|_{W_2^l(G)}^2 &= \sum_{|j| < l} \|D^j u\|_{L_2(G)}^2 + \\ &+ \sum_{|j| = [l]} \int_G \int_G \frac{|D^j u(x) - D^j u(y)|^2}{|x - y|^{n+2(l-[l])}} dx dy. \end{aligned}$$

Now we define an anisotropic spaces  $W_2^{l,l/2}(Q_T)$  ( $Q_T = \Omega \times (0, T)$ ) consisting of functions  $u(x, t)$  ( $(x, t) \in Q_T$ ) by  $W_2^{l,l/2}(Q_T) = L_2(0, T; W_2^l(\Omega)) \cap L_2(\Omega; W_2^{l/2}(0, T))$  and introduce in this space the norm

$$\|u\|_{W_2^{l,l/2}(Q_T)}^2 = \int_0^t \|u(\cdot, t)\|_{W_2^l(\Omega)}^2 dt + \int_\Omega \|u(x, \cdot)\|_{W_2^{l/2}(0, T)}^2 dx.$$

The same notation will be used for the spaces of vector fields, the norms of a vector supposed to be equal to the sum of all its components.

Let us first state local solvability of the problem (1.4), (1.5). Transforming the problem to the initial domain  $\Omega_0$  by the relation

$$(1.6) \quad x = \xi + \int_0^t \hat{v}(\xi, \tau) d\tau \equiv x(\xi, t),$$

where  $\hat{v}(\xi, t)$  is the velocity vector field in Lagrangean coordinate system, we have

**Theorem 1.1 (local existence)** *Let  $b \in W_2^{5/2+l}(\mathbf{R}^2)$  with  $l \in (1/2, 1)$ . For arbitrary  $\rho_0, v_0, \theta_0 \in W_2^{2+l}(\Omega_0)$ ,  $\rho_0 + \bar{\rho}, \theta_0 + \bar{\theta} > 0$ ,  $F_0 \in W_2^{7/2+l}(\mathbf{R}^2)$ ,  $\theta_e \in W_2^{4+l, 2+l/2}(\mathbf{R}_T^3)$ ,  $\theta_a \in W_2^{5/2+l, 5/4+l/2}(\Sigma_T)$ ,  $\theta_e + \bar{\theta}, \theta_a + \bar{\theta} > 0$  satisfying natural compatibility conditions, which we omit them here, the problem (1.4), (1.5) in Lagrangean coordinate system has the unique solution  $(\hat{\rho}, \hat{v}, \hat{\theta})$   $(\xi, t)$  defined on  $Q_{T_1} \equiv \Omega_0 \times (0, T_1)$  for some  $T_1 \in (0, T)$  such that  $\hat{\rho} \in W_2^{2+l, 1+l/2}(Q_{T_1})$ ,  $\hat{v}, \hat{\theta} \in W_2^{3+l, 3/2+l/2}(Q_{T_1})$  and*

$$(1.7) \quad \begin{aligned} \hat{E}^{3+l}(Q_{T_1}) &\equiv \|\hat{\rho}\|_{W_2^{2+l, 1+l/2}(Q_{T_1})} + \|(\hat{v}, \hat{\theta})\|_{W_2^{3+l, 3/2+l/2}(Q_{T_1})} \leq \\ &\leq c_1 \left( \|(\rho_0, v_0, \theta_0)\|_{W_2^{2+l}(\Omega_0)} + \|F_0\|_{W_2^{7/2+l}(\mathbf{R}^2)} + \right. \\ &\quad \left. + \|\theta_e\|_{W_2^{4+l, 2+l/2}(\mathbf{R}_T^3)} + \|\theta_a\|_{W_2^{3/2+l, 3/4+l/2}(\Sigma_T)} \right) \equiv c_1 E_{0,T}. \end{aligned}$$

The number  $T_1$  increases unboundedly as  $E_{0,T}$  tends to zero. Moreover, the solution possesses some additional regularity with respect to  $t \geq t_1$ :

$$(1.8) \quad \sup_{t_1 < t < T_1} \left( \|\hat{\rho}\|_{W_2^{2+l}(\Omega_0)} + \|(\hat{v}, \hat{\theta})\|_{W_2^{3+l}(\Omega_0)} \right) \leq c_2 (E_{0,T} + \hat{E}^{3+l}(Q_{T_1})).$$

with arbitrary positive  $t_1 \leq T_1$ .

The proof of Theorem 1.1 can be carried out in the same way as in [5,8].

The following is our main theorem.

**Theorem 1.2 (global existence)** *Under the assumptions of theorem 1.1, if  $E_0 \equiv E_{0,\infty} \leq \varepsilon$  with sufficiently small number  $\varepsilon$ , then the problem (1.4), (1.5) has the unique solution  $(\rho, v, \theta, F)$  for all  $t > 0$  satisfying*

$$(1.9) \quad \sup_{t \geq t_1} \left( \|\rho\|_{W_2^{2+l}(\Omega_t)} + \|(v, \theta)\|_{W_2^{3+l}(\Omega_t)} + \|F\|_{W_2^{7/2+l}(\mathbf{R}^2)} \right) \leq c_3 E_0$$

with each  $t_1 > 0$ .

Similar result for barotropic fluid bounded only by a free surface was established in [6].

## 2 Proof of theorem 1.2.

Theorem 1.2 is proved by combination of the local existence theorem and the a priori estimate. To state the a priori estimate, it is convenient to make use of the coordinate transformation mapping from  $\Omega_t$  onto the equilibrium domain  $\bar{\Omega} \equiv \{y' \in \mathbf{R}^2, -b(y') < y_3 < 0\}$  defined by

$$(2.1) \quad (x_1, x_2, x_3) = (y_1, y_2, \tilde{F} + y_3(1 + \frac{\tilde{F}}{b})) \equiv x(y, t),$$

where  $\tilde{F}$  is the extension of  $F$  to  $\bar{\Omega} \times \mathbf{R}_+$  (see [1]). Let us put  $\tilde{f}(y, t) = f(x(y, t), t)$  and

$$\begin{aligned} \tilde{E}^{3+l}(\bar{Q}_T) \equiv & \|\tilde{\rho}\|_{W_2^{2+l, 1+l/2}(\bar{Q}_T)} + \|(\tilde{v}, \tilde{\theta})\|_{W_2^{3+l, 3/2+l/2}(\bar{Q}_T)} + \\ & + \|F\|_{W_2^{7/2+l, 7/4+l/2}(\mathbf{R}_T^2)}, \quad \bar{Q}_T = \bar{\Omega} \times (0, T). \end{aligned}$$

**Theorem 2.1 (a priori estimate)** *Let  $(\rho, v, \theta, F)$  be the solution of (1.4), (1.5) defined on  $0 < t < T$ . If  $E_{0,T} < \varepsilon_1$  and  $\tilde{E}^{3+l}(\bar{Q}_T) < \delta_1$  with sufficiently small  $\varepsilon_1, \delta_1$ , then the following a priori estimate holds:*

$$(2.2) \quad \tilde{E}^{3+l}(\bar{Q}_T) \leq c_4 E_{0,T}.$$

**Proof of Theorem 1.2.** Let  $E_0$  be so small that the problem (1.4), (1.5) is solvable on the interval  $(0, 1)$ . Such a solution satisfies inequalities (1.7), (1.8) for  $T_1 = 1$ . Furthermore, (2.2) with  $T = 1$  is valid provided that  $E_0 < \varepsilon_1$  and  $c_1 E_0 < \delta_1$ . Combining these inequalities, we find that  $E_1 \leq c_5 E_0$  ( $E_1$  is the norms of the data at  $t = 1$ ). Introducing new Lagrangean coordinate system  $\xi \in \Omega_1$  and again applying Theorem 1.1, we can establish the solvability of the problem for  $t \in (1, 2)$  provided that  $E_0$  is sufficiently small. Repeating this process infinitely many times, we arrive at the assertion of the theorem. ■

## 3 a priori estimate.

First we rewrite the system (1.4), (1.5) so that all the nonlinear terms appear in the right hand side of equations and next make transformation

to the equilibrium rest domain  $\bar{\Omega}$  and linearize it again. Then we finally obtain

$$(3.1) \quad \begin{cases} \tilde{\rho}_t + \bar{\rho}(\nabla \cdot \tilde{v}) + (\tilde{v} \cdot \nabla)\bar{\rho} = f^1, \\ \bar{\rho}\tilde{v}_t - \nabla \cdot \bar{V} + \bar{p}_\rho \nabla \tilde{\rho} + \bar{p}_\theta \nabla \tilde{\theta} - \\ \quad - \left( \frac{\bar{\rho}}{\bar{p}_\rho} (dp_\rho)_{(\bar{\rho}, \bar{\theta})}(\tilde{\rho}, \tilde{\theta}) - \tilde{\rho} \right) g e_3 = f^2, \\ \bar{\rho} \bar{c}_V \tilde{\theta}_t - \nabla \cdot (\bar{\kappa} \nabla \tilde{\theta}) + \bar{\theta} \bar{p}_\theta (\nabla \cdot \tilde{v}) = f^3, \quad \text{in } \bar{Q}_T, \end{cases}$$

$$(3.2) \quad \begin{cases} (\tilde{\rho}, \tilde{v}, \tilde{\theta})|_{t=0} = (\tilde{\rho}_0, \tilde{v}_0, \tilde{\theta}_0)(y), \quad \text{on } \bar{\Omega}, \\ \bar{\mu} \left( \frac{\partial \tilde{v}_k}{\partial y_3} + \frac{\partial \tilde{v}_3}{\partial y_k} \right) \Big|_{y_3=0} = f^{3+k}, \quad (k = 1, 2), \\ -(dp)_{(\bar{\rho}, \bar{\theta})}(\tilde{\rho}, \tilde{\theta}) + \bar{\mu}'(\nabla \cdot \tilde{v}) + 2\bar{\mu} \frac{\partial \tilde{v}_3}{\partial y_3} - \sigma \nabla'^2 F - \bar{p}'_0 F \Big|_{y_3=0} = f^6, \\ \bar{\kappa} \frac{\partial \tilde{\theta}}{\partial y_3} + \kappa_e \tilde{\theta} \Big|_{y_3=0} = \kappa_e \tilde{\theta}_e + f^7, \quad \text{on } \mathbf{R}_T^2, \\ \tilde{v} = 0, \quad \tilde{\theta} = \theta_a, \quad \text{on } \Sigma_T, \\ F_t - \tilde{v}_3|_{y_3=0} = f^8, \quad \text{on } \mathbf{R}_T^2, \quad F|_{t=0} = F_0(y'), \quad \text{on } \mathbf{R}^2, \end{cases}$$

where  $\bar{V} = \bar{\mu}'(\nabla \cdot \tilde{v})\mathbf{I} + 2\bar{\mu}\mathbf{D}(\tilde{v})$ ,  $\bar{p}'_0 = \frac{\partial}{\partial x_3} p(\bar{\rho}(x_3), \bar{\theta}) \Big|_{x_3=0}$  and  $f = \{f^i \ (i = 1, \dots, 8)\}$  is at least quadratic functions of  $(\tilde{\rho}, \tilde{v}, \tilde{\theta}, \tilde{F})$  and their first and second derivatives. The estimate of the linearized problem (3.1), (3.2) with given  $f$  reads as follows.

**Lemma 3.1** *Let  $b \in W_2^{3/2+l}$  with  $l \in (1/2, 1)$ ,  $\tilde{\rho}_0, \tilde{v}_0, \tilde{\theta}_0 \in W_2^{1+l}(\bar{\Omega})$ ,  $F_0 \in W_2^{5/2+l}(\mathbf{R}^2)$ ,  $f^1 \in W_2^{1+l, 1/2+l/2}(\bar{Q}_T)$ ,  $f^2, f^3 \in W_2^{l, l/2}(\bar{Q}_T)$ ,  $f^{3+k}, f^6, f^7 \in W_2^{1/2+l, 1/4+l/2}(\mathbf{R}_T^2)$ ,  $f^8 \in W_2^{3/2+l, 3/4+l/2}(\mathbf{R}_T^2)$ ,  $\theta_e \in W_2^{3+l, 3/2+l/2}(\mathbf{R}_T^3)$ ,  $\theta_a \in W_2^{3/2+l, 3/4+l/2}(\Sigma_T)$ . Then for the problem (3.1), (3.2), we have the estimate*

$$\begin{aligned}
(3.3) \quad & \|\tilde{\rho}\|_{W_2^{1+l,1/2+l/2}(\bar{Q}_T)} + \|(\tilde{v}, \tilde{\theta})\|_{W_2^{2+l,1+l/2}(\bar{Q}_T)} + \|F\|_{W_2^{5/2+l,5/4+l/2}(R_T^2)} \leq \\
& \leq c_6 \left( \|(\tilde{\rho}_0, \tilde{v}_0, \tilde{\theta}_0)\|_{W_2^{1+l}(\bar{\Omega})} + \|F_0\|_{W_2^{5/2+l}(R^2)} + \right. \\
& \quad + \|f^1\|_{W_2^{1+l,1/2+l/2}(\bar{Q}_T)} + \|(f^2, f^3)\|_{W_2^{l,l/2}(\bar{Q}_T)} + \\
& \quad + \|(f^{3+k}, f^6, f^7)\|_{W_2^{1/2+l,1/4+l/2}(R_T^2)} + \|f^8\|_{W_2^{3/2+l,3/4+l/2}(R_T^2)} + \\
& \quad \left. + \|\theta_e\|_{W_2^{3+l,3/2+l/2}(R_T^3)} + \|\theta_a\|_{W_2^{3/2+l,3/4+l/2}(\Sigma_T)} \right).
\end{aligned}$$

We can prove Lemma 3.1 by similar argument as in [4].

Let us proceed to the proof of Theorem 2.1. First of all, estimating the norms of  $f$  in the right hand side of (3.3), we have

$$\tilde{E}^{2+l}(\bar{Q}_T) \leq c_7 \left( E_{0,T} + \delta_1 \tilde{E}^{2+l}(\bar{Q}_T) + (\tilde{E}^{2+l}(\bar{Q}_T))^2 \right)$$

which implies

$$(3.4) \quad \tilde{E}^{2+l}(\bar{Q}_T) \leq 2c_7 E_{0,T}$$

provided that the numbers  $\varepsilon_1$  and  $\delta_1$  are small enough  $2c_7\delta_1 + 4c_7^2\varepsilon_1 < 1$ . Next we rewrite the problem for  $\tilde{\theta}$  as

$$\left\{ \begin{array}{l} \bar{\rho} \bar{c}_V \tilde{\theta}_t - \bar{\kappa} \nabla^2 \tilde{\theta} = f^3 - \bar{\theta} \bar{p}_\rho (\nabla \cdot \tilde{v}) - \\ \quad - \bar{\kappa} \nabla^2 \tilde{\theta} + \nabla \cdot (\bar{\kappa} \nabla \tilde{\theta}) \equiv f'^3, \quad \text{in } \bar{Q}_T, \\ \tilde{\theta}|_{t=0} = \tilde{\theta}_0(y), \quad \text{on } \bar{\Omega}, \\ \bar{\kappa} \frac{\partial \tilde{\theta}}{\partial y_3} \Big|_{y_3=0} = \kappa_e (\tilde{\theta}_e - \tilde{\theta}) + f^7 \equiv f'^7, \quad \text{on } R_T^2, \\ \tilde{\theta} = \theta_a, \quad \text{on } \Sigma_T, \end{array} \right.$$



and apply the well-known estimate for the heat equation to obtain

$$\begin{aligned} \|\tilde{\theta}\|_{W_2^{3+l,3/2+l/2}(\bar{Q}_T)} &\leq c_8 \left( \|\tilde{\theta}_0\|_{W_2^{2+l}(\bar{\Omega})} + \|f'^3\|_{W_2^{1+l,1/2+l/2}(\bar{Q}_T)} + \right. \\ &\quad \left. + \|f'^7\|_{W_2^{3/2+l,3/4+l/2}(R_T^2)} + \|\theta_a\|_{W_2^{5/2+l,5/4+l/2}(\Sigma_T)} \right) \\ &\leq c_9 \left( E_{0,T} + \delta_1 \|\tilde{\theta}\|_{W_2^{3+l,3/2+l/2}(\bar{Q}_T)} \right), \end{aligned}$$

here, of course, we have used (3.4). Hence the estimate

$$(3.5) \quad \|\tilde{\theta}\|_{W_2^{3+l,3/2+l/2}(\bar{Q}_T)} \leq 2c_9 E_{0,T}$$

follows provided  $c_9 \delta_1 < \frac{1}{2}$ .

Finally, for the estimate of highest derivatives of  $(\tilde{\rho}, \tilde{v}, F)$ , we appeal to the energy method. The idea is similar to that of Matsumura and Nishida ([3]) but we use finite differences since we work our problem in fractional power spaces ([6]). It is convenient for a moment to rewrite the problem for  $(\tilde{\rho}, \tilde{v}, F)$  as

$$(3.6) \quad \begin{cases} \mathcal{L}^1(\tilde{\rho}, \tilde{v}) \equiv \frac{\tilde{D}\tilde{\rho}}{Dt} + \bar{\rho}(\nabla \cdot \tilde{v}) = g^1, \\ \mathcal{L}^2(\tilde{\rho}, \tilde{v}) \equiv \bar{\rho}\tilde{v}_t - \nabla \cdot \bar{\mathbf{P}}(\tilde{\rho}, \tilde{v}) = g^2, \quad \text{in } \bar{Q}_T, \\ \bar{\mathbf{P}}(\tilde{\rho}, \tilde{v})e_3 - \sigma \nabla'^2 F e_3|_{y_3=0} = g^3, \quad \tilde{v}|_{\Sigma} = 0, \\ F_t - \tilde{v}_3|_{y_3=0} = g^4 \end{cases}$$

where  $\frac{\tilde{D}}{Dt} = \frac{\partial}{\partial t} - (B \cdot \tilde{\nabla}) + (\tilde{v} \cdot \tilde{\nabla})$ ,  $\tilde{\nabla} = \tilde{A} \nabla_y$ ,  $\tilde{A} = {}^t \left( \frac{\partial x_i}{\partial y_j} \right)^{-1}_{1 \leq i, j \leq 3}$ ,  $B = \left( \frac{\partial x_i}{\partial t} \right)_{1 \leq i \leq 3}$ ,  $\bar{\mathbf{P}}(\tilde{\rho}, \tilde{v}) = (-\bar{p}_\rho \tilde{\rho} + \bar{\mu}'(\nabla \cdot \tilde{v}))\mathbf{I} + 2\bar{\mu}\mathbf{D}(\tilde{v})$  and here and in what follows, the terms  $g^i (i = 1, 2, \dots)$  being thus defined. We shall begin with the estimates of the derivatives with respect to  $t$ . Let us put

$$\Delta_t^k(h)\tilde{f}(y, t) = \sum_{j=0}^k C_k^j (-1)^{k-j} \tilde{f}(y, t + jh),$$

$k > \frac{1}{2}(1+l)$ ,  $C_k^j = \binom{k}{j}$  and let  $\varphi(t)$  be a smooth function vanishing for  $t \leq t_0$  and equals to 1 for  $t \geq 2t_0$ .

**Lemma 3.2** For  $(\tilde{\rho}, \tilde{v}, F)$  the inequalities

$$(3.7) \quad \int_0^{h_0} \frac{dh}{h^{2+l}} \left[ \varphi(t) \int_{\tilde{\Omega}} (|\Delta_t^k(h) \tilde{\rho}|^2 + |\Delta_t^k(h) \tilde{v}|^2) dy \right]_{T-kh_0} \leq \\ \leq c_{10} \left( E_{0,T}^2 + \int_0^{h_0} \frac{dh}{h^{2+l}} \int_0^{T-kh_0} \varphi(t) (|S_0| + |G_0|) dt \right),$$

$$(3.8) \quad \int_0^{h_0} \frac{dh}{h^{2+l}} \int_0^{T-kh_0} \varphi(t) dt \int_{\tilde{\Omega}} (|\Delta_t^k(h) \tilde{\rho}|^2 + |\Delta_t^k(h) \tilde{v}|^2) dy + \\ + \int_0^{h_0} \frac{dh}{h^{2+l}} \int_0^{T-kh_0} \varphi(t) dt \int_{R^2} (|\Delta_t^{k+1/4}(h) F_t|^2 dy' \leq \\ \leq c_{11} \left( E_{0,T}^2 + \int_0^{h_0} \frac{dh}{h^{2+l}} \left[ \varphi(t) \int_{\tilde{\Omega}} |\Delta_t^k(h) \tilde{\rho}|^2 dy \right]_{T-kh_0} + \right. \\ \left. + \int_0^{h_0} \frac{dh}{h^{2+l}} \int_0^{T-kh_0} \varphi(t) (|S_1| + |G_1| + |G'_1|) dt \right),$$

hold true, where

$$S_i = \int_{R^2} \Delta_t^k(h) \partial_t^i \tilde{v} \cdot \bar{\mathbf{P}}(\Delta_t^k(h) \tilde{\rho}, \Delta_t^k(h) \tilde{v}) e_3 dy',$$

$$G_i = \int_{\tilde{\Omega}} \left( \frac{\bar{p}_\rho}{\bar{\rho}} \Delta_t^k(h) \partial_t^i \tilde{\rho} \cdot \Delta_t^k(h) g'^1 + \Delta_t^k(h) \partial_t^i \tilde{v} \cdot \Delta_t^k(h) g^2 \right) dy, \quad (i = 0, 1),$$

$$G'_1 = \int_{R^2} \Delta_t^{k+1/4}(h) F_t \cdot \Delta_t^{k+1/4}(h) g^4 dy', \quad g'^1 = g^1 - \frac{\tilde{D}\tilde{\rho}}{Dt}$$

and we have assumed  $T > \max\{kh_0, 2t_0\}$ .

*proof* The identities

$$\frac{\bar{p}_\rho}{\bar{\rho}} \Delta_t^k(h) \tilde{\rho} \cdot \Delta_t^k(h) (\mathcal{L}^1 - g^1) + \Delta_t^k(h) \tilde{v} \cdot \Delta_t^k(h) (\mathcal{L}^2 - g^2) = 0,$$

$$\Delta_t^k(h) \tilde{\rho}_t \cdot \Delta_t^k(h) (\mathcal{L}^1 - g^1) + \Delta_t^k(h) \tilde{v}_t \cdot \Delta_t^k(h) (\mathcal{L}^2 - g^2) + \\ + \Delta_t^{k+1/4}(h) F_t \cdot \Delta_t^{k+1/4}(h) (F_t - \tilde{v} - g^4) = 0$$

yield the estimates (3.7), (3.8) respectively by integration by parts. This completes the proof of Lemma 3.2. ■

The estimates of the derivatives with respect to  $y$  are derived from local considerations. We only consider here near the upper surface, since the case of the interior domain or near the lower bottom are easier. We introduce local rectangular coordinate system with the origin at some point  $y^{(k)} = (y'^{(k)}, 0) \in \bar{\Gamma} \equiv \{y_3 = 0\}$  in a parallel direction with  $\{y\}$  axes and consider the subdomains

$$\begin{aligned}\bar{\omega}^{(k)} &= \{|y' - y'^{(k)}| \leq d, -2d \leq y_3 \leq 0\}, \\ \bar{\Omega}^{(k)} &= \{|y' - y'^{(k)}| \leq 2d, -4d \leq y_3 \leq 0\} \quad (d > 0)\end{aligned}$$

and the associated smooth functions  $\zeta^{(k)} \in C_0^\infty(\mathbf{R}^3)$  such that  $\zeta^{(k)}(y) = 1$  if  $y \in \omega^{(k)}$ ,  $= 0$  if  $y \in \bar{\Omega} - \bar{\Omega}^{(k)}$  and  $0 \leq \zeta^{(k)} \leq 1$ . The similar argument as Lemma 3.2 yields the estimate of the differences to tangential direction

$$\Delta^s(z')\tilde{f}(y, t) = \sum_{k=0}^s C_s^k (-1)^{s-k} \tilde{f}(y' + kz', y_3, t) \quad (s > 2 + l).$$

**Lemma 3.3** *For any positive number  $\varepsilon_2$  it holds that*

$$\begin{aligned}(3.9) \quad & \int_{|z| \leq \frac{d}{s}} \frac{dz}{z^{3+2l}} \int_{\bar{\Omega}^{(k)}} (|\Delta^s(z')\tilde{\rho}_t|^2 + |\Delta^s(z')\tilde{v}_t|^2) \zeta^{(k)2} dy + \\ & + \int_0^t \int_{|z| \leq \frac{d}{s}} \frac{dz}{z^{3+2l}} \int_{\bar{\Omega}^{(k)}} (|\nabla \Delta^s(z')\tilde{v}|^2 + |\Delta^s(z') \frac{\tilde{D}\tilde{\rho}}{Dt}|^2) \zeta^{(k)2} dy \leq \\ & \leq c_{12} \left( E_{0,T}^2 + \varepsilon_2 \int_0^t dt \int_{|z| \leq \frac{d}{s}} \frac{dz}{z^{3+2l}} \int_{\bar{\Omega}^{(k)}} |\Delta^s(z')\tilde{\rho}|^2 dy + \right. \\ & \left. + \int_0^t \int_{|z| \leq \frac{d}{s}} \frac{(|S_2| + |G_2|)}{z^{3+2l}} dz \right),\end{aligned}$$

where

$$\begin{aligned}S_2 &= \int_{R^2} \Delta^s(z')\tilde{v} \cdot \bar{\mathbf{P}}(\Delta^s(z')\tilde{\rho}, \Delta^s(z')\tilde{v}) e_3 \zeta^{(k)2} dy', \\ G_2 &= \int_{\bar{\Omega}^{(k)}} \left( \frac{\bar{p}_\rho}{\bar{\rho}} \Delta^s(z')\tilde{\rho} \cdot \Delta^s(z')g^{1'} + \Delta^s(z')\tilde{v} \cdot \Delta^s(z')g^2 \right) \zeta^{(k)2} dy.\end{aligned}$$

We proceed to estimate the differences to normal direction in the line with [3]. This time we rewrite the equation (3.6)<sub>2</sub> in the form

$$(3.10) \quad \bar{\rho} \tilde{v}_t - \bar{\mu} \nabla^2 \tilde{v} - (\bar{\mu} + \bar{\mu}') \nabla (\nabla \cdot \tilde{v}) + \bar{p}_\rho \nabla \tilde{\rho} = g^5.$$

If we eliminate  $\tilde{v}_{3,y_3y_3}$  from the third component of (3.10) and

$$\left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3} + \bar{\rho}(\nabla \cdot \tilde{v})_{y_3} = g_{y_3}^1 - [\nabla_{y_3}, \bar{\rho}] \nabla \cdot \tilde{v} \equiv g^6,$$

we have

$$\begin{aligned} \frac{(2\bar{\mu} + \bar{\mu}')}{\bar{\rho}} \left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3} + \bar{p}_\rho \tilde{\rho}_{y_3} &= -\bar{\rho} \tilde{v}_{3,t} + \frac{(2\bar{\mu} + \bar{\mu}')}{\bar{\rho}} g^6 + \\ &+ \bar{\mu}(\tilde{v}_{3,y_1y_1} + \tilde{v}_{3,y_2y_2}) - \bar{\mu}(\tilde{v}_{1,y_1} + \tilde{v}_{2,y_2})_{y_3} + g_3^5 \equiv g^7. \end{aligned}$$

Further, operating  $\Delta^k(z')\Delta^m(z_3)$  yields

$$\begin{aligned} (3.11) \quad &\frac{(2\bar{\mu} + \bar{\mu}')}{\bar{\rho}} \Delta^k(z')\Delta^m(z_3) \left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3} + \bar{p}_\rho \Delta^k(z')\Delta^m(z_3) \tilde{\rho}_{y_3} = \\ &= \Delta^k(z')\Delta^m(z_3) g^7 - \Delta^k(z')[\Delta^m(z_3), \frac{(2\bar{\mu} + \bar{\mu}')}{\bar{\rho}}] \left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3} - \\ &- \Delta^k(z')[\Delta^m(z_3), \bar{p}_\rho] \tilde{\rho}_{y_3} \equiv g^8. \end{aligned}$$

Multiplying (3.11) by  $\Delta^k(z')\Delta^m(z_3)\tilde{\rho}_{y_3}$  and  $\Delta^k(z')\Delta^m(z_3)\left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3}$  and adding them, we have

### Lemma 3.4

$$\begin{aligned} (3.12) \quad &\int_{|z| \leq \frac{d}{s}} \frac{dz}{z^{3+2l}} \int_{\bar{\Omega}^{(k)}} (|\Delta^s(z')\Delta^m(z_3)\tilde{\rho}_{y_3}|^2 \zeta^{(k)2} dy + \\ &+ \int_0^t \int_{|z| \leq \frac{d}{s}} \frac{dz}{z^{3+2l}} \int_{\bar{\Omega}^{(k)}} (|\Delta^s(z')\Delta^m(z_3)\tilde{\rho}_{y_3}|^2 + \\ &+ |\Delta^s(z')\Delta^m(z_3) \left(\frac{\tilde{D}\tilde{\rho}}{Dt}\right)_{y_3}|^2) \zeta^{(k)2} dy \leq \\ &\leq c_{13} \left( E_{0,T}^2 + \int_0^t \int_{|z| \leq \frac{d}{s}} \frac{(|G_3| + |G'_3| + |G_4|)}{z^{3+2l}} dz \right), \end{aligned}$$

where

$$\begin{aligned}
G_3 &= \int_{\bar{\Omega}^{(k)}} \Delta^s(z') \Delta^m(z_3) \tilde{\rho}_{y_3} \cdot g^8 \zeta^{(k)2} dy, \\
G'_3 &= \int_{\bar{\Omega}^{(k)}} \Delta^s(z') \Delta^m(z_3) \left( \frac{\tilde{D}\tilde{\rho}}{Dt} \right)_{y_3} \cdot g^8 \zeta^{(k)2} dy, \\
G_4 &= \int_{\bar{\Omega}^{(k)}} \Delta^s(z') \Delta^m(z_3) \left( \left( \frac{\tilde{D}\tilde{\rho}}{Dt} \right)_{y_3} - \tilde{\rho}_{ty_3} \right) \cdot \Delta^s(z') \Delta^m(z_3) \tilde{\rho}_{y_3} \zeta^{(k)2} dy.
\end{aligned}$$

Finally, we consider incompressible Stokes system for  $(u, q, \eta) \equiv \zeta^{(k)} \Delta^k(z')(\tilde{\rho}, \tilde{v}, F)$ , which reduces to the form

$$(3.13) \quad \begin{cases} \nabla \cdot u = g^9 \equiv \nabla \cdot g'^9, \\ \bar{\rho} u_t - \bar{\mu} \nabla^2 u + \bar{p}_\rho \nabla q = g^{10}, \quad \text{in } \bar{Q}_T^{(k)} \equiv \bar{\Omega}^{(k)} \times (0, T), \\ u|_{t=0} \equiv u_o, \\ -\bar{p}_\rho \nabla q \mathbf{I} e_3 + 2\bar{\mu} \mathbf{D}(u) e_3 - \sigma \nabla'^2 \eta|_{y_3=0} = g^{11}, \\ \eta_t - u_3 = g^{12}. \end{cases}$$

Applying the estimate analogous to (3.3), we obtain

$$\begin{aligned}
& \|\zeta^{(k)} \Delta^k(z') \nabla \tilde{\rho}\|_{W_2^{m,m/2}(\bar{Q}_T^{(k)})} + \|\zeta^{(k)} \Delta^k(z') \tilde{v}\|_{W_2^{2+m,1+m/2}(\bar{Q}_T^{(k)})} + \\
& + \|\zeta^{(k)} \Delta^k(z') F\|_{W_2^{5/2+m,5/4+m/2}(R_T^2)} \leq \\
(3.14) \quad & \leq c_{14} \left( \|\zeta^{(k)} \Delta^k(z') \tilde{v}_0\|_{W_2^{1+m}(\bar{\Omega}^{(k)})} + \|\zeta^{(k)} \Delta^k(z') F_0\|_{W_2^{5/2+m}(R^2)} + \right. \\
& + \|g^9\|_{W_2^{1+m,1/2+m/2}(\bar{Q}_T^{(k)})} + \|g'^9\|_{W_2^{0,1+m/2}(\bar{Q}_T^{(k)})} + \|g^{10}\|_{W_2^{m,m/2}(\bar{Q}_T^{(k)})} + \\
& \left. + \|g^{11}\|_{W_2^{1/2+m,1/4+m/2}(R_T^2)} + \|g^{12}\|_{W_2^{3/2+m,3/4+m/2}(R_T^2)} \right).
\end{aligned}$$

From (3.4), (3.5) and Lemmas 3.2-3.5 together with some lengthy calculations connected with the terms in the right hand side of (3.7)-(3.14), we arrive (2.2). This completes the proof of Theorem 2.1.  $\blacksquare$

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